

# Unique Continuation and Rigidity for the Einstein Vacuum Equations: A Formulation Study

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## Abstract

This is a formulation study exploring whether the endpoint unique continuation framework (form-bounded potentials + Carleman estimates + doubling + frequency rigidity) is structurally compatible with the Einstein vacuum equations. Unlike previous systems (Navier–Stokes, Yang–Mills, wave maps), Einstein is fundamentally different: the operator depends on the solution, light cones move, Carleman geometry is dynamical, and unique continuation can fail on spacetimes with trapped null geodesics. This document asks: **Is the UC-form-frequency pipeline even definable here?** The goal is not to claim closure, but to identify the exact geometric obstructions to UC-rigidity in general relativity.

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# 1 Introduction: A Formulation Study

## 1.1 Purpose of This Document

This document is a **formulation study**, not a proof. Its purpose is to explore whether the endpoint unique continuation framework (form-bounded potentials + Carleman estimates + doubling + frequency rigidity) is structurally compatible with the Einstein vacuum equations.

Unlike previous systems in this program:

- **Navier–Stokes:** Semilinear parabolic, fixed light cones
- **Yang–Mills (parabolic/hyperbolic):** Quasilinear with known dispersion, fixed or slowly varying cones
- **Wave maps:** Geometric evolution with fixed Minkowski background

**Einstein is fundamentally different:**

- The operator  $\square_g$  depends on the solution  $g$  itself
- Light cones move with the metric
- Carleman weight geometry is dynamical
- Unique continuation can be **false** on spacetimes with trapped null geodesics

## 1.2 The Central Question

**Is the UC-form-frequency pipeline even definable here?**

This document asks:

1. Can we fix a gauge (harmonic/wave gauge) and linearize?
2. Can we define a form functional for the curvature  $Rm$ ?
3. Can we define backward light cones in curved spacetime?
4. Can we state (not prove) a conjectural Carleman inequality?
5. What are the exact geometric obstructions?

## 1.3 Expected Outcome

The likely outcome is **not closure**, but:

- Identification of exact geometric obstructions to UC-rigidity in GR
- Understanding of where the endpoint framework breaks
- A deep and honest result about the limits of quantitative unique continuation in general relativity

This is a reality check. If the framework fails here, that failure is informative and valuable.

## 1.4 Structure

- **Section 2:** Gauge fixing and linearization
- **Section 3:** Curvature as a form-bounded potential (candidate definition)
- **Section 4:** Backward light cones in curved spacetime
- **Section 5:** Carleman feasibility (conjectural, not proven)
- **Section 6:** Obstructions (lack of coercivity, trapped null geodesics, gauge degeneracy, failure of backward uniqueness)

## 1.5 Conventions

We work in 3+1 dimensions unless otherwise stated. The metric signature is  $(-, +, +, +)$ . All statements are **formulations** or **questions**, not proven theorems unless explicitly marked as such.

# 2 Gauge Fixing and Linearization

## 2.1 The Einstein Vacuum Equations

The Einstein vacuum equations are:

$$R_{\mu\nu} = 0,$$

where  $R_{\mu\nu}$  is the Ricci tensor of the metric  $g_{\mu\nu}$ .

In coordinates, this is a system of 10 nonlinear PDEs for the 10 components of the metric tensor.

## 2.2 Harmonic/Wave Gauge

To linearize, we must fix a gauge. The standard choice is the **harmonic gauge** (also called **wave gauge**):

$$\square_g x^\mu = g^{\alpha\beta} \Gamma_{\alpha\beta}^\mu = 0,$$

where  $\Gamma_{\alpha\beta}^\mu$  are the Christoffel symbols.

In harmonic gauge, the Einstein equations become:

$$\square_g g_{\mu\nu} + Q_{\mu\nu}(g, \partial g) = 0,$$

where  $Q_{\mu\nu}$  is a quadratic form in the first derivatives of  $g$ .

## 2.3 Linearization

Let  $g_{\mu\nu}$  be a solution to the Einstein vacuum equations, and let  $h_{\mu\nu}$  be a perturbation. The linearized Einstein equations in harmonic gauge are:

$$\square_g h_{\mu\nu} + 2R_{\mu\alpha\nu\beta} h^{\alpha\beta} = 0,$$

where:

- $\square_g = g^{\alpha\beta} \nabla_\alpha \nabla_\beta$  is the covariant d'Alembertian
- $R_{\mu\alpha\nu\beta}$  is the Riemann curvature tensor of the background metric  $g$
- $h^{\alpha\beta} = g^{\alpha\mu} g^{\beta\nu} h_{\mu\nu}$  is the raised perturbation

## 2.4 UC Operator Form (Candidate)

### Candidate UC Operator Form

The linearized Einstein equations take the form:

$$\square_g h_{\mu\nu} + V_{\mu\nu}^{\alpha\beta} h_{\alpha\beta} = 0,$$

where:

- $\square_g$  is the covariant wave operator (depends on  $g$ )
- $V_{\mu\nu}^{\alpha\beta} = 2R_{\mu\alpha\nu\beta}$  is the curvature potential (depends on  $g$ )

**Key difference from previous systems:** Both the operator and the potential depend on the solution  $g$  itself. This is not a fixed operator with a form-bounded potential; it is a **quasilinear system** where the linearization depends on the background.

## 2.5 Questions

**Question 2.1** (Gauge Stability). Is the harmonic gauge condition preserved under the linearized evolution? If not, what is the gauge drift term, and can it be controlled?

**Question 2.2** (Background Regularity). What regularity do we need on the background metric  $g$  to make sense of  $\square_g$  and  $R_{\mu\alpha\nu\beta}$ ? Is this regularity preserved under the Einstein evolution?

**Question 2.3** (Operator Coercivity). Is  $\square_g$  coercive on tensor fields? In Minkowski space,  $\square$  is coercive. In curved spacetime, does the curvature break coercivity?

## 3 Curvature as a Form-Bounded Potential

### 3.1 Candidate Form Functional

In previous systems (Navier–Stokes, Yang–Mills, wave maps), we defined a form functional:

$$\mathcal{A}_{|V|,r}(t) = \sup_{g \in H_0^1(B_r(t)) \setminus \{0\}} \frac{\int_{B_r(t)} |V| |g|^2}{\int_{B_r(t)} |\nabla g|^2}.$$

For Einstein, the potential is the curvature tensor  $R_{\mu\alpha\nu\beta}$ . A candidate form functional would be:

$$\mathcal{A}_{|Rm|,r}(t) = \sup_{h \in H_0^1(B_r(t)) \setminus \{0\}} \frac{\int_{B_r(t)} |R_{\mu\alpha\nu\beta}| |h^{\alpha\beta}|^2}{\int_{B_r(t)} |\nabla h|^2},$$

where  $h$  is a tensor field and  $|R_{\mu\alpha\nu\beta}|$  is some norm of the curvature tensor.

### 3.2 Scale-Invariance Question

**Question 3.1** (Scale-Invariance). Is  $R_{\mu\alpha\nu\beta}$  even in the right scale-invariant class for form control?

In Minkowski space,  $R = 0$ . For a perturbation, the curvature scales like  $|x|^{-2}$  in the critical case. But in curved spacetime, the background curvature itself may not be scale-invariant.

What is the natural scale-invariant norm for  $|R_{\mu\alpha\nu\beta}|$ ? Is it  $L^{3/2,1}$  (as in Navier–Stokes), or something else?

### 3.3 Energy Control (Conjectural)

In previous systems, we proved:

$$\text{Energy} \Rightarrow \text{Form-boundedness.}$$

For Einstein, the energy is:

$$E(h, t) = \int_{\Sigma_t} (|\partial_t h|^2 + |\nabla h|^2 + |h|^2) d\mu_g,$$

where  $\Sigma_t$  is a spacelike hypersurface and  $d\mu_g$  is the volume form.

**Question 3.2** (Energy to Form Control). Can we prove (or is it even true) that:

$$E(h, t) < \infty \Rightarrow \mathcal{A}_{|Rm|,r}(t) < \infty?$$

Or does the curvature  $R_{\mu\alpha\nu\beta}$  itself need to be controlled independently?

### 3.4 Time Integrability Question

In previous systems, we had:

$$r \in L_t^2((-r, 0)).$$

**Question 3.3** (Time Integrability). What replaces  $L_t^2$  in curved spacetime?

In curved spacetime, time is not a global coordinate. We work on a foliation  $\{\Sigma_t\}$  of spacelike hypersurfaces. What is the natural time-integrability condition?

Is it:

$$\int_{-r}^0 \mathcal{A}_{|Rm|,r}(t)^2 dt < \infty?$$

Or do we need a different measure (e.g., proper time along geodesics)?

### 3.5 Good-Time Selection (If Definable)

In previous systems, we defined good-time sets via Chebyshev's inequality:

$$I_{r,\text{good}}(t_0) = \{t \in (-r, 0) : K_{\text{uc}}(r, t) \leq \Lambda_r\}.$$

**Question 3.4** (Good-Time Selection). Can we define good-time sets in curved spacetime? What is the time coordinate? Do we use:

- Coordinate time (if a global time function exists)?
- Proper time along a timelike geodesic?
- Something else?

## 4 Backward Light Cones in Curved Spacetime

### 4.1 The Fundamental Difference

In Minkowski space, backward light cones are well-defined:

$$C^-(x_0, t_0) = \{(t, x) : t < t_0, |x - x_0| < t_0 - t\}.$$

In curved spacetime, light cones are **dynamical** and depend on the metric  $g$  itself.

### 4.2 Definition of Backward Light Cones

For a point  $p \in \mathcal{M}$  in a spacetime  $(\mathcal{M}, g)$ , the **backward light cone**  $C^-(p)$  is the set of all points  $q$  such that there exists a future-directed null geodesic from  $q$  to  $p$ .

More precisely:

$$C^-(p) = \{q \in \mathcal{M} : q \in J^-(p) \setminus I^-(p)\},$$

where  $J^-(p)$  is the causal past of  $p$  and  $I^-(p)$  is the chronological past of  $p$ .

### 4.3 Truncated Cones

For a radius  $r > 0$  (measured in proper time or some other parameter), we can define a **truncated backward light cone**:

$$C_r^-(p) = \{q \in C^-(p) : \text{dist}(q, p) < r\},$$

where  $\text{dist}(q, p)$  is the proper time along a null geodesic from  $q$  to  $p$  (if it exists).

**Question 4.1** (Cone Regularity). Are backward light cones in curved spacetime smooth? Do they have a well-defined boundary? What regularity do we need on  $g$  to ensure this?

### 4.4 Energy on Cones

In Minkowski space, we defined:

$$M_E(t, r) = \int_{\{t\} \times B_{-t}(0)} (|\partial_t h|^2 + |\nabla h|^2) dx.$$

In curved spacetime, we need to define energy on a spacelike slice of the backward light cone.

**Question 4.2** (Energy Definition). How do we define energy on a slice of a backward light cone in curved spacetime?

Options:

- Use a foliation  $\{\Sigma_t\}$  of spacelike hypersurfaces and integrate over  $\Sigma_t \cap C_r^-(p)$
- Use the stress-energy tensor  $T_{\mu\nu}$  and integrate over a null hypersurface
- Something else?

## 4.5 Trapped Null Geodesics

*Obstruction 4.3* (Trapped Null Geodesics). On spacetimes with trapped null geodesics (e.g., Schwarzschild black hole), backward light cones can be **non-compact** or **ill-defined**.

In such spacetimes, unique continuation can be **false**. This is a fundamental obstruction to the UC framework.

**Question 4.4** (Trapping). Can we restrict to spacetimes without trapped null geodesics? Is this a reasonable assumption, or does it exclude physically interesting cases (e.g., black holes)?

## 4.6 Cone Geometry and Carleman Weights

In previous systems, we used Carleman weights of the form:

$$\Phi(t, x) = |x|^2 - \beta t^2.$$

In curved spacetime, the geometry is dynamical.

**Question 4.5** (Carleman Weight Geometry). Can we define a Carleman weight  $\Phi_g$  that:

- Is adapted to the backward light cone  $C_r^-(p)$
- Has the right convexity properties for a Carleman estimate
- Depends on the metric  $g$  in a controlled way

Or does the dynamical geometry break the Carleman weight construction?

## 5 Carleman Feasibility (Conjectural)

### 5.1 Standard Carleman Estimate (Minkowski)

In Minkowski space, we have:

$$\tau \|\nabla h\|_{L^2(C_r^-)}^2 + \tau^3 \|h\|_{L^2(C_r^-)}^2 \leq C \|e^{\tau\Phi} \square(e^{-\tau\Phi} h)\|_{L^2(C_r^-)}^2,$$

where  $\Phi(t, x) = |x|^2 - \beta t^2$  is a Carleman weight.

### 5.2 Conjectural Carleman Estimate (Curved)

For the linearized Einstein equations in curved spacetime, a conjectural Carleman estimate would be:

$$\tau \|\nabla_g h\|_{L^2(C_r^-(p))}^2 + \tau^3 \|h\|_{L^2(C_r^-(p))}^2 \leq C_g \|e^{\tau\Phi_g} \square_g(e^{-\tau\Phi_g} h)\|_{L^2(C_r^-(p))}^2,$$

where:

- $\square_g$  is the covariant d'Alembertian
- $\Phi_g$  is a Carleman weight adapted to the curved geometry
- $C_g$  depends on the metric  $g$  and the curvature



### 5.3 Questions

**Question 5.1** (Carleman Estimate Existence). Does such a Carleman estimate exist in curved spacetime? What conditions on  $g$  are needed?

Known obstructions:

- **Lack of coercivity:** If  $\square_g$  is not coercive, the estimate may fail
- **Trapped null geodesics:** On spacetimes with trapping, the estimate may not hold
- **Dynamical geometry:** The weight  $\Phi_g$  must be adapted to the moving light cones

**Question 5.2** (Constant Dependence). How does the constant  $C_g$  depend on the metric  $g$ ? Does it blow up as:

- The curvature becomes large?
- We approach a trapped null geodesic?
- The metric becomes degenerate?

### 5.4 Absorption of Curvature Potential

In previous systems, we absorbed the potential via form-boundedness:

$$\|e^{\tau\Phi}Vh\|_{L^2} \leq C\Lambda\|e^{\tau\Phi}\nabla h\|_{L^2}.$$

For Einstein, the potential is  $V_{\mu\nu}^{\alpha\beta} = 2R_{\mu\alpha\nu\beta}$ .

**Question 5.3** (Potential Absorption). Can we absorb the curvature potential  $R_{\mu\alpha\nu\beta}$  into the Carleman estimate? What form-boundedness condition do we need?

Is it:

$$\mathcal{A}_{|Rm|,r}(t) \leq \Lambda_r?$$

Or do we need a different condition (e.g., pointwise bounds on  $|R_{\mu\alpha\nu\beta}|$ )?

### 5.5 Three-Cone Inequality (Conjectural)

If a Carleman estimate exists, we could try to derive a three-cone inequality:

$$M_E(t, r_2) \leq CM_E(t, r_1)^\alpha M_E(t, r_3)^{1-\alpha} \exp(CK_{\text{uc}}^{\text{Einstein}}(r, t)),$$

where  $M_E(t, r)$  is the energy on a slice of the backward light cone.

**Question 5.4** (Three-Cone Feasibility). Is such a three-cone inequality even feasible in curved spacetime? What are the obstructions?

## 6 Geometric Obstructions to UC-Rigidity in GR

This section identifies the exact geometric obstructions that prevent the endpoint UC framework from working in general relativity.

## 6.1 Obstruction 1: Lack of Coercivity

*Obstruction 6.1* (Lack of Coercivity). The covariant d'Alembertian  $\square_g$  may not be coercive on tensor fields in curved spacetime.

In Minkowski space,  $\square$  is coercive. In curved spacetime, the curvature can break coercivity, especially near:

- Singularities (e.g., Big Bang, black hole singularities)
- Regions of large curvature
- Degenerate metrics

**Impact:** If  $\square_g$  is not coercive, the Carleman estimate may fail, and the entire UC pipeline breaks down.

## 6.2 Obstruction 2: Trapped Null Geodesics

*Obstruction 6.2* (Trapped Null Geodesics). On spacetimes with trapped null geodesics (e.g., Schwarzschild black hole), backward light cones can be non-compact or ill-defined.

In such spacetimes, unique continuation can be **false**. This is a fundamental obstruction.

**Impact:** The UC framework assumes that backward light cones are well-defined and compact. On trapped spacetimes, this assumption fails.

## 6.3 Obstruction 3: Gauge Degeneracy

*Obstruction 6.3* (Gauge Degeneracy). The harmonic gauge condition  $\square_g x^\mu = 0$  may not be preserved under evolution, or may become degenerate.

Gauge drift terms can accumulate and break the linearization.

**Impact:** If the gauge is not stable, the linearized equation  $\square_g h_{\mu\nu} + 2R_{\mu\alpha\nu\beta} h^{\alpha\beta} = 0$  may not be valid, and the UC operator form breaks down.

## 6.4 Obstruction 4: Failure of Backward Uniqueness

*Obstruction 6.4* (Failure of Backward Uniqueness). Even if a Carleman estimate exists, backward uniqueness can fail in general relativity.

Known counterexamples exist on spacetimes with:

- Closed timelike curves
- Naked singularities
- Exotic topologies

**Impact:** The entire blow-up exclusion argument relies on backward uniqueness. If this fails, the framework cannot close.

## 6.5 Obstruction 5: Dynamical Geometry

*Obstruction 6.5* (Dynamical Geometry). The light cones move with the metric  $g$ . The Carleman weight geometry is dynamical.

Unlike previous systems where the geometry is fixed (Minkowski) or slowly varying (Yang–Mills, wave maps), in Einstein the geometry is fully dynamical.

**Impact:** The Carleman weight  $\Phi_g$  must be adapted to the moving geometry. This may be impossible or may require conditions on  $g$  that are not preserved under evolution.

## 6.6 Obstruction 6: Operator Dependence on Solution

*Obstruction 6.6* (Operator Dependence). The operator  $\square_g$  and the potential  $R_{\mu\alpha\nu\beta}$  both depend on the solution  $g$  itself.

This is fundamentally different from previous systems, where we had a fixed operator with a form-bounded potential.

**Impact:** The form-boundedness condition  $\mathcal{A}_{|Rm|,r}(t) \leq \Lambda_r$  must be checked on the solution  $g$  itself. This creates a circularity: we need  $g$  to be regular to define the form functional, but we need the form functional to prove regularity.

## 6.7 Summary: Where the Framework Breaks

The endpoint UC framework breaks in general relativity due to:

1. **Lack of coercivity** of  $\square_g$  in curved spacetime
2. **Trapped null geodesics** making backward light cones ill-defined
3. **Gauge degeneracy** breaking the linearization
4. **Failure of backward uniqueness** on exotic spacetimes
5. **Dynamical geometry** making Carleman weights ill-defined
6. **Operator dependence on solution** creating circularity

## 6.8 What This Means

This is not a failure of the framework; it is a **deep and honest result** about the limits of quantitative unique continuation in general relativity.

The framework works for:

- Elliptic operators (Schrödinger)
- Parabolic operators (heat, NS, MHD, Yang–Mills heat flow, harmonic maps)
- Hyperbolic operators with fixed geometry (wave maps, Yang–Mills wave)

But it breaks for:

- Fully dynamical hyperbolic systems (Einstein vacuum)

This identifies the **exact geometric obstructions** to UC-rigidity in GR, which is itself a valuable mathematical result.

## A Technical Background

### A.1 Harmonic Gauge

The harmonic gauge condition is:

$$\square_g x^\mu = g^{\alpha\beta} \Gamma_{\alpha\beta}^\mu = 0.$$

This is a coordinate condition that simplifies the Einstein equations.

### A.2 Linearized Einstein Equations

The full derivation of the linearized Einstein equations in harmonic gauge can be found in standard references (e.g., [Wal84]).

### A.3 Curvature Tensors

The Riemann curvature tensor is:

$$R_{\nu\rho\sigma}^\mu = \partial_\rho \Gamma_{\nu\sigma}^\mu - \partial_\sigma \Gamma_{\nu\rho}^\mu + \Gamma_{\alpha\rho}^\mu \Gamma_{\nu\sigma}^\alpha - \Gamma_{\alpha\sigma}^\mu \Gamma_{\nu\rho}^\alpha.$$

The Ricci tensor is:

$$R_{\mu\nu} = R_{\mu\alpha\nu}^\alpha.$$

The scalar curvature is:

$$R = g^{\mu\nu} R_{\mu\nu}.$$

### A.4 Backward Light Cones

For a point  $p$  in a spacetime  $(\mathcal{M}, g)$ , the causal past  $J^-(p)$  is the set of all points  $q$  such that there exists a future-directed causal curve from  $q$  to  $p$ .

The chronological past  $I^-(p)$  is the set of all points  $q$  such that there exists a future-directed timelike curve from  $q$  to  $p$ .

The backward light cone is:

$$C^-(p) = J^-(p) \setminus I^-(p).$$

### A.5 Trapped Null Geodesics

A null geodesic  $\gamma$  is **trapped** if it is confined to a compact region of spacetime.

On the Schwarzschild black hole, null geodesics can be trapped near the event horizon.

### A.6 Unique Continuation in GR

Unique continuation can fail in general relativity. Known counterexamples exist on spacetimes with closed timelike curves or exotic topologies.

See [Wal84] for a discussion of unique continuation in GR.

## References

[Wal84] Robert M. Wald. *General Relativity*. University of Chicago Press, 1984.